

ECUACIÓN DE CONTINUIDAD $\boxed{\frac{\partial \rho}{\partial t} + \nabla \cdot \underline{v} = 0}$

Coordenadas Rectangulares (x ; y ; z): $\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} (\rho V_x) + \frac{\partial}{\partial y} (\rho V_y) + \frac{\partial}{\partial z} (\rho V_z) = 0$

Coordenadas Cilíndricas (r ; θ ; z): $\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r} (\rho r V_r) + \frac{1}{r} \frac{\partial}{\partial \theta} (\rho V_\theta) + \frac{\partial}{\partial z} (\rho V_z) = 0$

Coordenadas Esféricas (r ; θ ; Φ): $\frac{\partial \rho}{\partial t} + \frac{1}{r^2} \frac{\partial}{\partial r} (\rho r^2 V_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\rho V_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (\rho V_\phi) = 0$

ECUACIÓN DE MOVIMIENTO

$$\rho \left(\frac{\partial \underline{V}}{\partial t} + \underline{V} \cdot (\nabla \underline{V}) \right) = -\nabla p - \nabla \tau + \rho \cdot \underline{g}$$

$$\rho \left(\frac{\partial \underline{V}}{\partial t} + \underline{V} \cdot (\nabla \underline{V}) \right) = -\nabla p + \nabla^2 \underline{V} + \rho \cdot \underline{g}$$

1) RECTANGULARES (x ; y ; z)

1-1) En función de τ :

Componente x $\rho \left(\frac{\partial V_x}{\partial t} + V_x \frac{\partial V_x}{\partial x} + V_y \frac{\partial V_x}{\partial y} + V_z \frac{\partial V_x}{\partial z} \right) = -\frac{\partial p}{\partial x} - \left(\frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} \right) + \rho g_x$

Componente y $\rho \left(\frac{\partial V_y}{\partial t} + V_x \frac{\partial V_y}{\partial x} + V_y \frac{\partial V_y}{\partial y} + V_z \frac{\partial V_y}{\partial z} \right) = -\frac{\partial p}{\partial y} - \left(\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} \right) + \rho g_y$

Componente z $\rho \left(\frac{\partial V_z}{\partial t} + V_x \frac{\partial V_z}{\partial x} + V_y \frac{\partial V_z}{\partial y} + V_z \frac{\partial V_z}{\partial z} \right) = -\frac{\partial p}{\partial z} - \left(\frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} \right) + \rho g_z$

1-2) En función de los gradientes de velocidad para fluidos newtoniano de ρ y μ ctes:

Componente x $\rho \left(\frac{\partial V_x}{\partial t} + V_x \frac{\partial V_x}{\partial x} + V_y \frac{\partial V_x}{\partial y} + V_z \frac{\partial V_x}{\partial z} \right) = -\frac{\partial p}{\partial x} + \mu \left(\frac{\partial^2 V_x}{\partial x^2} + \frac{\partial^2 V_x}{\partial y^2} + \frac{\partial^2 V_x}{\partial z^2} \right) + \rho g_x$

Componente y $\rho \left(\frac{\partial V_y}{\partial t} + V_x \frac{\partial V_y}{\partial x} + V_y \frac{\partial V_y}{\partial y} + V_z \frac{\partial V_y}{\partial z} \right) = -\frac{\partial p}{\partial y} + \mu \left(\frac{\partial^2 V_y}{\partial x^2} + \frac{\partial^2 V_y}{\partial y^2} + \frac{\partial^2 V_y}{\partial z^2} \right) + \rho g_y$

Componente z $\rho \left(\frac{\partial V_z}{\partial t} + V_x \frac{\partial V_z}{\partial x} + V_y \frac{\partial V_z}{\partial y} + V_z \frac{\partial V_z}{\partial z} \right) = -\frac{\partial p}{\partial z} + \mu \left(\frac{\partial^2 V_z}{\partial x^2} + \frac{\partial^2 V_z}{\partial y^2} + \frac{\partial^2 V_z}{\partial z^2} \right) + \rho g_z$

2) CILÍNDRICAS (r ; θ ; z)

2-1) En función de τ:

Componente r $\rho \left(\frac{\partial V_r}{\partial t} + V_r \frac{\partial V_r}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_r}{\partial \theta} - \frac{V_\theta^2}{r} + V_z \frac{\partial V_r}{\partial z} \right) = -\frac{\partial p}{\partial r} - \left(\frac{1}{r} \frac{\partial}{\partial r} (\tau r) + \frac{1}{r} \frac{\partial \tau_\theta}{\partial \theta} - \frac{\tau_\theta}{r} + \frac{\partial \tau_z}{\partial z} \right) + \rho g_r$

Componente θ $\rho \left(\frac{\partial V_\theta}{\partial t} + V_r \frac{\partial V_\theta}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{V_r V_\theta}{r} + V_z \frac{\partial V_\theta}{\partial z} \right) = -\frac{1}{r} \frac{\partial p}{\partial \theta} - \left(\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_\theta) + \frac{1}{r} \frac{\partial \tau_{\theta\theta}}{\partial \theta} + \frac{\partial \tau_{z\theta}}{\partial z} \right) + \rho g_\theta$

Componente z $\rho \left(\frac{\partial V_z}{\partial t} + V_r \frac{\partial V_z}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_z}{\partial \theta} + V_z \frac{\partial V_z}{\partial z} \right) = -\frac{\partial p}{\partial z} - \left(\frac{1}{r^2} \frac{\partial}{\partial r} (r \tau_{rz}) + \frac{1}{r} \frac{\partial \tau_{z\theta}}{\partial \theta} + \frac{\partial \tau_{zz}}{\partial z} \right) + \rho g_z$

2-2) En función de los gradientes de velocidad para fluidos newtoniano de ρ y μ ctes:

Componente r $\rho \left(\frac{\partial V_r}{\partial t} + V_r \frac{\partial V_r}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_r}{\partial \theta} - \frac{V_\theta^2}{r} + V_z \frac{\partial V_r}{\partial z} \right) = -\frac{\partial p}{\partial r} + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (r V_r) \right) + \frac{1}{r^2} \frac{\partial^2 V_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial V_\theta}{\partial \theta} + \frac{\partial^2 V_r}{\partial z^2} \right) + \rho g_r$

Componente θ $\rho \left(\frac{\partial V_\theta}{\partial t} + V_r \frac{\partial V_\theta}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{V_r V_\theta}{r} + V_z \frac{\partial V_\theta}{\partial z} \right) = -\frac{1}{r} \frac{\partial p}{\partial \theta} + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (r V_\theta) \right) + \frac{1}{r^2} \frac{\partial^2 V_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial V_r}{\partial \theta} + \frac{\partial^2 V_\theta}{\partial z^2} \right) + \rho g_\theta$

Componente z $\rho \left(\frac{\partial V_z}{\partial t} + V_r \frac{\partial V_z}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_z}{\partial \theta} + V_z \frac{\partial V_z}{\partial z} \right) = -\frac{\partial p}{\partial z} + \mu \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V_z}{\partial \theta^2} + \frac{\partial^2 V_z}{\partial z^2} \right) + \rho g_z$

3) ESFÉRICAS (r ; θ ; φ)

3-1) En función de τ:

Componente r $\rho \left(\frac{\partial V_r}{\partial t} + V_r \frac{\partial V_r}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_r}{\partial \theta} + \frac{V_\phi}{r \sin \theta} \frac{\partial V_r}{\partial \phi} - \frac{V_\theta^2 + V_\phi^2}{r} \right) = -\frac{\partial p}{\partial r} - \left(\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\tau_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial \tau_\phi}{\partial \phi} - \frac{\tau_\theta}{r} + \frac{\tau_\phi}{r} \right) + \rho g_r$

Componente θ $\rho \left(\frac{\partial V_\theta}{\partial t} + V_r \frac{\partial V_\theta}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{V_\phi}{r \sin \theta} \frac{\partial V_\theta}{\partial \phi} + \frac{V_r V_\theta}{r} - \frac{V_\phi^2 \cot \theta}{r} \right) = -\frac{1}{r} \frac{\partial p}{\partial \theta} - \left(\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_\theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\tau_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial \tau_{\theta\phi}}{\partial \phi} + \frac{\tau_\theta}{r} - \frac{\cot \theta}{r} \tau_\phi \right) + \rho g_\theta$

Componente φ $\rho \left(\frac{\partial V_\phi}{\partial t} + V_r \frac{\partial V_\phi}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_\phi}{\partial \theta} + \frac{V_\phi}{r \sin \theta} \frac{\partial V_\phi}{\partial \phi} + \frac{V_\phi V_r}{r} + \frac{V_\phi V_\theta}{r} \cot \theta \right) = -\frac{1}{r \sin \theta} \frac{\partial p}{\partial \phi} - \left(\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_\phi) + \frac{1}{r} \frac{\partial \tau_\theta}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \tau_{\theta\phi}}{\partial \phi} + \frac{\tau_\phi}{r} + \frac{2 \cot \theta}{r} \tau_\theta \right) + \rho g_\phi$

3-2) En función de los gradientes de velocidad para fluidos newtoniano de ρ y μ ctes::

Componente r $\rho \left(\frac{\partial V_r}{\partial t} + V_r \frac{\partial V_r}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_r}{\partial \theta} + \frac{V_\phi}{r \sin \theta} \frac{\partial V_r}{\partial \phi} - \frac{V_\theta^2 + V_\phi^2}{r} \right) = -\frac{\partial p}{\partial r} + \mu \left(\nabla^2 V_r - \frac{2}{r^2} V_r - \frac{2}{r^2} \frac{\partial V_\theta}{\partial \theta} - \frac{2}{r^2} V_\theta \cot \theta - \frac{2}{r^2 \sin \theta} \frac{\partial V_\phi}{\partial \phi} \right) + \rho g_r$

Componente θ $\rho \left(\frac{\partial V_\theta}{\partial t} + V_r \frac{\partial V_\theta}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{V_\phi}{r \sin \theta} \frac{\partial V_\theta}{\partial \phi} + \frac{V_r V_\theta}{r} - \frac{V_\phi^2 \cot \theta}{r} \right) = -\frac{1}{r} \frac{\partial p}{\partial \theta} + \mu \left(\nabla^2 V_\theta + \frac{2}{r^2} \frac{\partial V_r}{\partial \theta} - \frac{V_\theta}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial V_\phi}{\partial \phi} \right) + \rho g_\theta$

Componente z $\rho \left(\frac{\partial V_\phi}{\partial t} + V_r \frac{\partial V_\phi}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_\phi}{\partial \theta} + \frac{V_\phi}{r \sin \theta} \frac{\partial V_\phi}{\partial \phi} + \frac{V_\phi V_r}{r} + \frac{V_\phi V_\theta}{r} \cot \theta \right) = -\frac{1}{r \sin \theta} \frac{\partial p}{\partial \phi} + \mu \left(\nabla^2 V_\phi - \frac{V_\phi}{r^2 \sin^2 \theta} + \frac{2}{r^2 \sin \theta} \frac{\partial V_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial V_\theta}{\partial \phi} \right) + \rho g_\phi$

En estas Ecuaciones

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin \theta} \left(\frac{\partial^2}{\partial \phi^2} \right)$$

COMPONENTES DEL TENSOR ESFUERZO $\underline{\underline{\tau}}$

Coordenadas Rectangulares (x ; y ; z):

$\tau_{xx} = -\mu \left[2 \frac{\partial V_x}{\partial x} - \frac{2}{3} (\nabla \cdot \underline{V}) \right]$	$\tau_{xy} = \tau_{yx} = -\mu \left[\frac{\partial V_x}{\partial y} + \frac{\partial V_y}{\partial x} \right]$
$\tau_{yy} = -\mu \left[2 \frac{\partial V_y}{\partial y} - \frac{2}{3} (\nabla \cdot \underline{V}) \right]$	$\tau_{yz} = \tau_{zy} = -\mu \left[\frac{\partial V_y}{\partial z} + \frac{\partial V_z}{\partial y} \right]$
$\tau_{zz} = -\mu \left[2 \frac{\partial V_z}{\partial z} - \frac{2}{3} (\nabla \cdot \underline{V}) \right]$	$\tau_{zx} = \tau_{xz} = -\mu \left[\frac{\partial V_z}{\partial x} + \frac{\partial V_x}{\partial z} \right]$

$$(\nabla \cdot \underline{V}) = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$$

Coordenadas Cilíndricas (r ; θ ; z):

$\tau_{rr} = -\mu \left[2 \frac{\partial V_r}{\partial r} - \frac{2}{3} (\nabla \cdot \underline{V}) \right]$	$\tau_{r\theta} = \tau_{\theta r} = -\mu \left[r \frac{\partial}{\partial r} \left(\frac{V_\theta}{r} \right) + \frac{1}{r} \frac{\partial V_r}{\partial \theta} \right]$
$\tau_{\theta\theta} = -\mu \left[2 \left(\frac{1}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{V_r}{r} \right) - \frac{2}{3} (\nabla \cdot \underline{V}) \right]$	$\tau_{\theta z} = \tau_{z\theta} = -\mu \left[\frac{\partial V_\theta}{\partial z} + \frac{1}{r} \frac{\partial V_z}{\partial \theta} \right]$
$\tau_{zz} = -\mu \left[2 \frac{\partial V_z}{\partial z} - \frac{2}{3} (\nabla \cdot \underline{V}) \right]$	$\tau_{zr} = \tau_{rz} = -\mu \left[\frac{\partial V_z}{\partial r} + \frac{\partial V_r}{\partial z} \right]$

$$(\nabla \cdot \underline{V}) = \frac{1}{r} \frac{\partial}{\partial r} (r V_r) + \frac{1}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{\partial V_z}{\partial z}$$

Coordenadas Esféricas (r ; θ ; Φ):

$\tau_{rr} = -\mu \left[2 \frac{\partial V_r}{\partial r} - \frac{2}{3} (\nabla \cdot \underline{V}) \right]$	$\tau_{r\theta} = \tau_{\theta r} = -\mu \left[r \frac{\partial}{\partial r} \left(\frac{V_\theta}{r} \right) + \frac{1}{r} \frac{\partial V_r}{\partial \theta} \right]$
$\tau_{\theta\theta} = -\mu \left[2 \left(\frac{1}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{V_r}{r} \right) - \frac{2}{3} (\nabla \cdot \underline{V}) \right]$	$\tau_{\theta\phi} = \tau_{\phi\theta} = -\mu \left[\frac{\text{sen}\theta}{r} \frac{\partial}{\partial \theta} \left(\frac{V_\phi}{\text{sen}\theta} \right) + \frac{1}{r \text{sen}\theta} \frac{\partial V_\theta}{\partial \phi} \right]$
$\tau_{\phi\phi} = -\mu \left[2 \left(\frac{1}{r \text{sen}\theta} \frac{\partial V_\phi}{\partial \phi} + \frac{V_r}{r} + \frac{V_\theta \cot\theta}{r} \right) - \frac{2}{3} (\nabla \cdot \underline{V}) \right]$	$\tau_{\phi r} = \tau_{r\phi} = -\mu \left[\frac{1}{r \text{sen}\theta} \frac{\partial V_r}{\partial \phi} + \frac{\partial}{\partial r} \left(\frac{V_\phi}{r} \right) \right]$

$$(\nabla \cdot \underline{V}) = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_r) + \frac{1}{r \text{sen}\theta} \frac{\partial}{\partial \theta} (V_\theta \text{sen}\theta) + \frac{1}{r \text{sen}\theta} \frac{\partial V_\phi}{\partial \phi}$$

RESUMEN DE OPERACIONES DIFERENCIALES CON EL OPERADOR ∇ RECTANGULARES ($x ; y ; z$)

$$(\underline{\nabla} \cdot \underline{V}) = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$$

$$(\nabla^2 s) = \frac{\partial^2 s}{\partial x^2} + \frac{\partial^2 s}{\partial y^2} + \frac{\partial^2 s}{\partial z^2}$$

$$(\underline{\tau} : \underline{\nabla V}) = \tau_{xx} \left(\frac{\partial V_x}{\partial x} \right) + \tau_{yy} \left(\frac{\partial V_y}{\partial y} \right) + \tau_{zz} \left(\frac{\partial V_z}{\partial z} \right) + \tau_{xy} \left(\frac{\partial V_x}{\partial y} + \frac{\partial V_y}{\partial x} \right) + \tau_{yz} \left(\frac{\partial V_y}{\partial z} + \frac{\partial V_z}{\partial y} \right) + \tau_{zx} \left(\frac{\partial V_z}{\partial x} + \frac{\partial V_x}{\partial z} \right)$$

$$[\underline{\nabla} s] \begin{cases} [\underline{\nabla} s]_x = \frac{\partial s}{\partial x} \\ [\underline{\nabla} s]_y = \frac{\partial s}{\partial y} \\ [\underline{\nabla} s]_z = \frac{\partial s}{\partial z} \end{cases} \quad [\underline{\nabla} \wedge \underline{V}] \begin{cases} [\underline{\nabla} \wedge \underline{V}]_x = \frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z} \\ [\underline{\nabla} \wedge \underline{V}]_y = \frac{\partial V_x}{\partial z} - \frac{\partial V_z}{\partial x} \\ [\underline{\nabla} \wedge \underline{V}]_z = \frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \end{cases}$$

$$[\underline{\nabla} \cdot \underline{\tau}] \begin{cases} [\underline{\nabla} \cdot \underline{\tau}]_x = \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z} \\ [\underline{\nabla} \cdot \underline{\tau}]_y = \frac{\partial \tau_{yx}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{yz}}{\partial z} \\ [\underline{\nabla} \cdot \underline{\tau}]_z = \frac{\partial \tau_{zx}}{\partial x} + \frac{\partial \tau_{zy}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} \end{cases} \quad \nabla^2 \underline{V} \begin{cases} [\nabla^2 \underline{V}]_x = \frac{\partial^2 V_x}{\partial x^2} + \frac{\partial^2 V_x}{\partial y^2} + \frac{\partial^2 V_x}{\partial z^2} \\ [\nabla^2 \underline{V}]_y = \frac{\partial^2 V_y}{\partial x^2} + \frac{\partial^2 V_y}{\partial y^2} + \frac{\partial^2 V_y}{\partial z^2} \\ [\nabla^2 \underline{V}]_z = \frac{\partial^2 V_z}{\partial x^2} + \frac{\partial^2 V_z}{\partial y^2} + \frac{\partial^2 V_z}{\partial z^2} \end{cases}$$

$$\underline{\nabla} \underline{V} = \begin{bmatrix} \frac{\partial V_x}{\partial x} & \frac{\partial V_y}{\partial x} & \frac{\partial V_z}{\partial x} \\ \frac{\partial V_x}{\partial y} & \frac{\partial V_y}{\partial y} & \frac{\partial V_z}{\partial y} \\ \frac{\partial V_x}{\partial z} & \frac{\partial V_y}{\partial z} & \frac{\partial V_z}{\partial z} \end{bmatrix} \quad \begin{array}{c} \left[\frac{\partial}{\partial x} \right] \\ \left[\frac{\partial}{\partial y} \right] \\ \left[\frac{\partial}{\partial z} \right] \end{array} \begin{array}{|c|c|c|} \hline [V_x] & [V_y] & [V_z] \\ \hline \frac{\partial V_x}{\partial x} & \frac{\partial V_y}{\partial x} & \frac{\partial V_z}{\partial x} \\ \hline \frac{\partial V_x}{\partial y} & \frac{\partial V_y}{\partial y} & \frac{\partial V_z}{\partial y} \\ \hline \frac{\partial V_x}{\partial z} & \frac{\partial V_y}{\partial z} & \frac{\partial V_z}{\partial z} \\ \hline \end{array} = [\underline{\nabla} \underline{V}]$$

$$[\underline{V} \cdot \underline{\nabla} \underline{V}] \begin{cases} [V \cdot \nabla V]_x = V_x \frac{\partial V_x}{\partial x} + V_y \frac{\partial V_x}{\partial y} + V_z \frac{\partial V_x}{\partial z} \\ [V \cdot \nabla V]_y = V_x \frac{\partial V_y}{\partial x} + V_y \frac{\partial V_y}{\partial y} + V_z \frac{\partial V_y}{\partial z} \\ [V \cdot \nabla V]_z = V_x \frac{\partial V_z}{\partial x} + V_y \frac{\partial V_z}{\partial y} + V_z \frac{\partial V_z}{\partial z} \end{cases}$$

RESUMEN DE OPERACIONES DIFERENCIALES CON EL OPERADOR ∇ CILÍNDRICAS ($r; \theta; z$):

$$(\nabla \cdot V) = \frac{1}{r} \frac{\partial}{\partial r} (rVr) + \frac{1}{r} \frac{\partial V\theta}{\partial \theta} + \frac{\partial Vz}{\partial z}$$

$$(\nabla^2 s) = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial s}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 s}{\partial \theta^2} + \frac{\partial^2 s}{\partial z^2}$$

$$(\underline{\tau} : \nabla V) =$$

$$\tau r \left(\frac{\partial Vr}{\partial r} \right) + \tau \theta \theta \left(\frac{1}{r} \frac{\partial V\theta}{\partial \theta} + \frac{Vr}{r} \right) + \tau z z \left(\frac{\partial Vz}{\partial z} \right) + \tau r \theta \left(r \frac{\partial}{\partial r} \left(\frac{V\theta}{r} \right) + \frac{1}{r} \frac{\partial Vr}{\partial \theta} \right) + \tau \theta z \left(\frac{1}{r} \frac{\partial Vz}{\partial \theta} + \frac{\partial V\theta}{\partial z} \right) + \tau rz \left(\frac{\partial Vz}{\partial r} + \frac{\partial Vr}{\partial z} \right)$$

$$[\nabla s] \begin{cases} [\nabla s]_r = \frac{\partial s}{\partial r} \\ [\nabla s]_\theta = \frac{1}{r} \frac{\partial s}{\partial \theta} \\ [\nabla s]_z = \frac{\partial s}{\partial z} \end{cases}$$

$$[\nabla \wedge V] \begin{cases} [\nabla \wedge V]_r = \frac{1}{r} \frac{\partial Vz}{\partial \theta} - \frac{\partial V\theta}{\partial z} \\ [\nabla \wedge V]_\theta = \frac{\partial Vr}{\partial z} - \frac{\partial Vz}{\partial r} \\ [\nabla \wedge V]_z = \frac{1}{r} \frac{\partial}{\partial r} (rV\theta) - \frac{1}{r} \frac{\partial Vr}{\partial \theta} \end{cases}$$

$$[\nabla \cdot \underline{\tau}] \begin{cases} [\nabla \cdot \underline{\tau}]_r = \frac{1}{r} \frac{\partial}{\partial r} (r\tau r) + \frac{1}{r} \frac{\partial \tau \theta}{\partial \theta} - \frac{1}{r} \tau \theta \theta + \frac{\partial \tau rz}{\partial z} \\ [\nabla \cdot \underline{\tau}]_\theta = \frac{1}{r} \frac{\partial \tau \theta \theta}{\partial \theta} + \frac{\partial \tau r \theta}{\partial r} + \frac{2}{r} \tau r \theta + \frac{\partial \tau \theta z}{\partial z} \\ [\nabla \cdot \underline{\tau}]_z = \frac{1}{r} \frac{\partial}{\partial r} (r\tau rz) + \frac{1}{r} \frac{\partial \tau \theta z}{\partial \theta} + \frac{\partial \tau z z}{\partial z} \end{cases}$$

$$\nabla^2 V \begin{cases} [\nabla^2 V]_r = \frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (rVr) \right) + \frac{1}{r^2} \frac{\partial^2 Vr}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial V\theta}{\partial \theta} + \frac{\partial^2 Vr}{\partial z^2} \\ [\nabla^2 V]_\theta = \frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (rV\theta) \right) + \frac{1}{r^2} \frac{\partial^2 V\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial Vr}{\partial \theta} + \frac{\partial^2 V\theta}{\partial z^2} \\ [\nabla^2 V]_z = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial Vz}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 Vz}{\partial \theta^2} + \frac{\partial^2 Vz}{\partial z^2} \end{cases}$$

$$[V \cdot \nabla V] \begin{cases} [V \cdot \nabla V]_r = Vr \frac{\partial Vr}{\partial r} + \frac{V\theta}{r} \frac{\partial Vr}{\partial \theta} - \frac{V\theta^2}{r} + Vz \frac{\partial Vr}{\partial z} \\ [V \cdot \nabla V]_\theta = Vr \frac{\partial V\theta}{\partial r} + \frac{V\theta}{r} \frac{\partial V\theta}{\partial \theta} + \frac{VrV\theta}{r} + Vz \frac{\partial V\theta}{\partial z} \\ [V \cdot \nabla V]_z = Vr \frac{\partial Vz}{\partial r} + \frac{V\theta}{r} \frac{\partial Vz}{\partial \theta} + Vz \frac{\partial Vz}{\partial z} \end{cases}$$

RESUMEN DE OPERACIONES DIFERENCIALES CON EL OPERADOR ∇ ESFÉRICAS ($r; \theta; \phi$):

$$(\nabla \cdot \underline{V}) = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_r) + \frac{1}{r \operatorname{sen}\theta} \frac{\partial}{\partial \theta} (V_\theta \operatorname{sen}\theta) + \frac{1}{r \operatorname{sen}\theta} \frac{\partial}{\partial \phi} (V_\phi)$$

$$(\nabla^2 s) = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial s}{\partial r} \right) + \frac{1}{r^2 \operatorname{sen}\theta} \frac{\partial}{\partial \theta} \left(\operatorname{sen}\theta \frac{\partial s}{\partial \theta} \right) + \frac{1}{r^2 \operatorname{sen}^2\theta} \frac{\partial^2 s}{\partial \phi^2}$$

$$(\underline{\tau} : \nabla \underline{V}) = \tau_r \left(\frac{\partial V_r}{\partial r} \right) + \tau_\theta \theta \left(\frac{1}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{V_r}{r} \right) + \tau_\phi \phi \left(\frac{1}{r \operatorname{sen}\theta} \frac{\partial V_\phi}{\partial \phi} + \frac{V_r}{r} + \frac{V_\theta \cot \theta}{r} \right) + \tau_\theta \theta \left(\frac{\partial V_\theta}{\partial r} + \frac{1}{r} \frac{\partial V_r}{\partial \theta} - \frac{V_\theta}{r} \right) + \tau_\phi \phi \left(\frac{\partial V_\phi}{\partial r} + \frac{1}{r \operatorname{sen}\theta} \frac{\partial V_r}{\partial \phi} - \frac{V_\phi}{r} \right) + \tau_\theta \theta \left(\frac{1}{r} \frac{\partial V_\phi}{\partial \theta} + \frac{1}{r \operatorname{sen}\theta} \frac{\partial V_\theta}{\partial \phi} - \frac{\cot \theta}{r} V_\phi \right)$$

$$[\nabla s] \begin{cases} [\nabla s]_r = \frac{\partial s}{\partial r} \\ [\nabla s]_\theta = \frac{1}{r} \frac{\partial s}{\partial \theta} \\ [\nabla s]_\phi = \frac{1}{r \operatorname{sen}\theta} \frac{\partial s}{\partial \phi} \end{cases} \quad [\nabla \wedge \underline{V}] \begin{cases} [\nabla \wedge \underline{V}]_r = \frac{1}{r \operatorname{sen}\theta} \frac{\partial}{\partial \theta} (V_\phi \operatorname{sen}\theta) - \frac{1}{r \operatorname{sen}\theta} \frac{\partial V_\theta}{\partial \phi} \\ [\nabla \wedge \underline{V}]_\theta = \frac{1}{r \operatorname{sen}\theta} \frac{\partial V_r}{\partial \phi} - \frac{1}{r} \frac{\partial}{\partial r} (r V_\phi) \\ [\nabla \wedge \underline{V}]_\phi = \frac{1}{r} \frac{\partial}{\partial r} (r V_\theta) - \frac{1}{r} \frac{\partial V_r}{\partial \theta} \end{cases}$$

$$[\nabla \cdot \underline{\tau}] \begin{cases} [\nabla \cdot \underline{\tau}]_r = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_r) + \frac{1}{r \operatorname{sen}\theta} \frac{\partial}{\partial \theta} (\tau_\theta \operatorname{sen}\theta) + \frac{1}{r \operatorname{sen}\theta} \frac{\partial \tau_\phi}{\partial \phi} - \frac{\tau_\theta \theta + \tau_\phi \phi}{r} \\ [\nabla \cdot \underline{\tau}]_\theta = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_\theta) + \frac{1}{r \operatorname{sen}\theta} \frac{\partial}{\partial \theta} (\tau_\theta \operatorname{sen}\theta) + \frac{1}{r \operatorname{sen}\theta} \frac{\partial \tau_\phi}{\partial \phi} + \frac{\tau_\theta}{r} - \frac{\cot \theta}{r} \tau_\phi \\ [\nabla \cdot \underline{\tau}]_\phi = \frac{1}{r^2} \frac{\partial}{\partial r} (r \tau_\phi) + \frac{1}{r} \frac{\partial \tau_\theta}{\partial \theta} + \frac{1}{r \operatorname{sen}\theta} \frac{\partial \tau_\phi}{\partial \phi} + \frac{\tau_\phi}{r} + \frac{2 \cot \theta}{r} \tau_\theta \end{cases}$$

$$\nabla^2 \underline{V} \begin{cases} [\nabla^2 V]_r = \nabla^2 V_r - \frac{2V_r}{r^2} - \frac{2}{r^2} \frac{\partial V_\theta}{\partial \theta} - \frac{2V_\theta \cot \theta}{r^2} - \frac{2}{r^2 \operatorname{sen}\theta} \frac{\partial V_\phi}{\partial \phi} \\ [\nabla^2 V]_\theta = \nabla^2 V_\theta - \frac{2}{r^2} \frac{\partial V_r}{\partial \theta} - \frac{V_\theta}{r^2 \operatorname{sen}^2\theta} - \frac{2 \cos \theta}{r^2 \operatorname{sen}^2\theta} \frac{\partial V_\phi}{\partial \phi} \\ [\nabla^2 V]_\phi = \nabla^2 V_\phi - \frac{V_\phi}{r^2 \operatorname{sen}^2\theta} + \frac{2}{r^2 \operatorname{sen}^2\theta} \frac{\partial V_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \operatorname{sen}^2\theta} \frac{\partial V_\theta}{\partial \phi} \end{cases}$$

$$[\underline{V} \cdot \nabla \underline{V}] \begin{cases} [\underline{V} \cdot \nabla \underline{V}]_r = V_r \frac{\partial V_r}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_r}{\partial \theta} + \frac{V_\phi}{r \operatorname{sen}\theta} \frac{\partial V_r}{\partial \phi} - \frac{V_\theta^2 + V_\phi^2}{r} \\ [\underline{V} \cdot \nabla \underline{V}]_\theta = V_r \frac{\partial V_\theta}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{V_\phi}{r \operatorname{sen}\theta} \frac{\partial V_\theta}{\partial \phi} + \frac{V_r V_\theta}{r} - \frac{V_\phi^2 \cot \theta}{r} \\ [\underline{V} \cdot \nabla \underline{V}]_\phi = V_r \frac{\partial V_\phi}{\partial r} + \frac{V_\theta}{r} \frac{\partial V_\phi}{\partial \theta} + \frac{V_\phi}{r \operatorname{sen}\theta} \frac{\partial V_\phi}{\partial \phi} + \frac{V_\phi V_r}{r} + \frac{V_\theta V_\phi \cot \theta}{r} \end{cases}$$

$$\nabla^4 = \frac{\partial^4}{\partial x^4} + 2 \frac{\partial^4}{\partial x^2 \partial y^2} + \frac{\partial^4}{\partial y^4}$$

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